# PAPER DETAILS

TITLE: The existence of extremal solutions to nonlinear fractional integro-differential equations with

advanced arguments

AUTHORS: Neda KHODABAKHSHI,S Mansour VAEZPOUR

PAGES: 1411-1420

ORIGINAL PDF URL: https://dergipark.org.tr/tr/download/article-file/644695

 $\int$  Hacettepe Journal of Mathematics and Statistics Volume 45 (5) (2016), 1411–1420

# The existence of extremal solutions to nonlinear fractional integro-differential equations with advanced arguments

Neda Khodabakhshi<sup>\*†</sup> and S. Mansour Vaezpour<sup>‡</sup>

#### Abstract

This paper deals with the existence of extremal solutions for nonlinear fractional integro-differential equations with advanced arguments. Our analysis rely on monotone iterative method based on upper and lower solutions. Also, we give an illustrative example in order to indicate the validity of our assumptions.

**Keywords:** Monotone iterative method, Riemann-Liouville fractional derivative, Upper and lower solutions.

2000 AMS Classification: Primary 26A33; Secondary 34K37.

 $Received: 10.06.2015 \quad Accepted: 11.11.2015 \quad Doi: 10.15672/\,\mathrm{HJMS.20164514285}$ 

### 1. Introduction

Fractional calculus is a branch of mathematical analysis, that provides integrals and derivatives of any arbitrary order and due to their multiple applications in many areas of science and engineering has grown extensively. [1, 3, 4, 7, 8, 9, 10, 11, 14, 15, 16, 17]. The monotone iterative method based on upper and lower solutions is a fruitful tools that provides an efficient mechanism to prove the existence results for nonlinear differential problems. We refer the reader to the book [5] and recent papers [2, 6, 12, 13, 18, 19, 20, 21, 22].

As far as we know, few authors consider the existence of extremal solutions for nonlinear Riemann-Liouville fractional integro-differential equations with advanced arguments. So this paper is devoted to study of the following nonlinear boundary value problem:

(1.1) 
$$\begin{cases} (D^{\alpha}x(t))' = f(t,x(t), D^{\alpha}x(t), D^{\beta}x(t), Tx(t), Sx(t)), & t \in J := [0,T], \\ D^{\alpha}x(0) = x^*, & t^{1-\alpha}x(t)|_{t=0} = 0, & 0 < \beta \le \alpha \le 1, \end{cases}$$

<sup>\*</sup>Department of Mathematics and Computer Sciences, Amirkabir University of Technology, Tehran, Iran. Email: khodabakhshi@aut.ac.ir

<sup>&</sup>lt;sup>†</sup>Corresponding Author.

<sup>&</sup>lt;sup>‡</sup>S. Mansour Vaezpour, Email: vaez@aut.ac.ir

where  $f \in C(J \times \mathbb{R}^5, \mathbb{R})$ ,

$$(Tx)(t) = \int_0^t k(t,s)x(s)ds, \quad (Sx)(t) = \int_0^T h(t,s)x(s)ds,$$

 $k(t,s) \in C[D,\mathbb{R}^+], \ h(t,s) \in C[[0,T]^2,\mathbb{R}^+], \ D = \{(t,s) \in \mathbb{R}^2 | 0 \le s \le t \le T\} \text{ and } D^{\alpha}, D^{\beta}$  are the Riemann-Liouville fractional derivatives.

The innovation of this study is that the nonlinear term f involve unknown function x(t) and it's Riemann-Liouville fractional derivatives with different orders and integral operators Tx, Sx. Therefore, from this point of view, we generalize some recent works. Moreover, with a suitable choice of upper and lower solutions and condition on function f, we obtain the existence of extremal solutions and also present iterative sequences which are convergent to them.

This paper is organized as follows: in section 2, some facts and results about fractional calculus are given, also we consider the existence of the extremal solutions for first order nonlinear differential equation, while in spire of [20] we prove the main result in section 3 and we conclude this paper by considering an example in section 4.

#### 2. Preliminaries and some lemmas

In this section, we present some definitions and results which will be needed later.

**2.1. Definition.** ([4]) The Riemann-Liouville fractional integral of order  $\alpha > 0$  of a function  $f:(0,\infty) \to \mathbb{R}$  is defined by

$$I^{\alpha}f(t) = \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} f(s) ds, \quad t > 0,$$

provided that the right-hand side is pointwise defined.

**2.2. Definition.** ([4]) The Riemann-Liouville fractional derivative of order  $\alpha > 0$  of a continuous function  $f: (0, \infty) \to \mathbb{R}$  is defined by

$$D^{\alpha}f(t) = \frac{1}{\Gamma(n-\alpha)} (\frac{d}{dt})^n \int_0^t (t-s)^{n-\alpha-1} f(s) ds \quad t > 0,$$

where  $n = [\alpha] + 1$ , provided that the right-hand side is pointwise defined. In particular, for  $\alpha = n$ ,  $D^n f(t) = f^{(n)}(t)$ .

1. Remark. The following properties are well known:

$$\begin{split} D^{\alpha}I^{\alpha}f(t) &= f(t), \ \alpha > 0, \ f(t) \in L^1(0,\infty), \\ D^{\beta}I^{\alpha}f(t) &= I^{\alpha-\beta}f(t), \ \alpha > \beta > 0, \ f(t) \in L^1(0,\infty). \end{split}$$

**2.1. Lemma.** ([4]) Let  $Re(\alpha) > 0$ ,  $n = [Re(\alpha)] + 1$  and let  $f_{n-\alpha}(t) = I^{n-\alpha}f(t)$  be the fractional integral of order  $n - \alpha$ . If  $f(t) \in L^1(0, T)$  and  $f_{n-\alpha} \in AC^m[0, T]$ , then we have the following equality

$$I^{\alpha}D^{\alpha}f(t) = f(t) - \sum_{i=1}^{n} \frac{f_{n-\alpha}^{(n-i)}(0)}{\Gamma(\alpha - i + 1)} t^{\alpha - i}.$$

**2.2. Lemma.** The nonlinear fractional differential equation (1.1) is equivalent to the following IVP:

(2.1) 
$$\begin{cases} u'(t) = f(t, I^{\alpha}u(t), u(t), I^{\alpha-\beta}u(t), T_1u(t), S_1u(t)), & t \in J, \\ u(0) = x^*, & 0 < \beta \le \alpha \le 1, \end{cases}$$

1412

where

$$T_{1}u(t) = \int_{0}^{t} k_{1}(t,s)u(s)ds, \quad S_{1}u(t) = \int_{0}^{T} h_{1}(t,s)u(s)ds,$$
$$k_{1}(t,s) = \int_{s}^{t} \frac{(\tau-s)^{\alpha-1}k(t,\tau)}{\Gamma(\alpha)}d\tau, \quad h_{1}(t,s) = \int_{s}^{T} \frac{(\tau-s)^{\alpha-1}h(t,\tau)}{\Gamma(\alpha)}d\tau.$$

*Proof.* Take  $D^{\alpha}x(t) = u(t)$  in (1.1), taking into account that  $t^{1-\alpha}x(t)|_{t=0} = 0$ , we get

$$x(t) = I^{\alpha}u(t) = \frac{1}{\Gamma(\alpha)} \int_0^t (t-\tau)^{\alpha-1} u(\tau) d\tau,$$

also

$$Tx(t) = T(I^{\alpha}u(t)) = \int_{0}^{t} k(t,s)(I^{\alpha}u(t))_{t=s}ds$$
  
$$= \int_{0}^{t} k(t,s) \Big(\int_{0}^{s} \frac{(s-\tau)^{\alpha-1}u(\tau)}{\Gamma(\alpha)}d\tau\Big)ds$$
  
$$= \int_{0}^{t} \Big(\int_{\tau}^{t} \frac{(s-\tau)^{\alpha-1}k(t,s)}{\Gamma(\alpha)}ds\Big)u(\tau)d\tau$$
  
$$= \int_{0}^{t} \Big(\int_{s}^{t} \frac{(\tau-s)^{\alpha-1}k(t,\tau)}{\Gamma(\alpha)}d\tau\Big)u(s)ds$$
  
$$= \int_{0}^{t} k_{1}(t,s)u(s)ds.$$

The same process can be repeated for S. So the proof is completed.

Presently, we prove a comparison result for the first order initial value problem (2.1). 2.3. Lemma. Let  $w \in C^1(J, \mathbb{R})$  satisfy the relations

(2.2) 
$$\begin{cases} w'(t) \ge -KL_{\alpha}w(t) - Lw(t) - ML_{\alpha-\beta}w(t) - NT_{1}w(t) - PS_{1}w(t), \\ w(0) \ge 0, \ 0 < \beta \le \alpha \le 1, \end{cases}$$

where  $K, L, M, N, P \ge 0$  are constants and  $L_{\alpha}w(t) = \int_0^t \frac{(t-s)^{\alpha-1}w(s)}{\Gamma(\alpha)} ds$ . If

(2.3) 
$$\int_0^T \left[ \frac{Kt^{\alpha}}{\Gamma(\alpha+1)} + L + \frac{Mt^{\alpha-\beta}}{\Gamma(\alpha-\beta+1)} + N \int_0^t k_1(t,s) ds + P \int_0^T h_1(t,s) ds \right] dt < 1.$$

Then  $w(t) \ge 0, \forall t \in J.$ 

*Proof.* Suppose  $w(t) \ge 0$  is not true, then there exists a  $t_0 \in (0, T]$  such that  $w(t_0) < 0$ . Let  $\max\{w(t) : 0 \le t \le t_0\} = \lambda$ , then  $\lambda \ge 0$ .

If  $\lambda = 0$ , the proof is similar to Lemma (2.1) of [20].

If  $\lambda > 0$ , then there exists a  $t_1 \in [0, t_0]$  such that  $w(t_1) = \lambda > 0$ . From (2.2), we have

$$w'(t) \ge -\lambda \Big[ \frac{Kt^{\alpha}}{\Gamma(\alpha+1)} + L + \frac{Mt^{\alpha-\beta}}{\Gamma(\alpha-\beta+1)} \\ + N \int_0^t k_1(t,s)ds + P \int_0^T h_1(t,s)ds \Big], \quad \forall t \in [0,t_0].$$

Thus, we have

$$w(t_0) = w(t_1) + \int_{t_1}^{t_0} w'(t)dt$$
  

$$\geq \lambda - \lambda \int_0^T \left[\frac{Kt^{\alpha}}{\Gamma(\alpha+1)} + L + \frac{Mt^{\alpha-\beta}}{\Gamma(\alpha-\beta+1)} + N \int_0^t k_1(t,s)ds + P \int_0^T h_1(t,s)ds\right]dt$$
  

$$= \lambda \left(1 - \int_0^T \left[\frac{Kt^{\alpha}}{\Gamma(\alpha+1)} + L + \frac{Mt^{\alpha-\beta}}{\Gamma(\alpha-\beta+1)} + N \int_0^t k_1(t,s)ds + P \int_0^T h_1(t,s)ds\right]dt\right).$$

Then, by  $w(t_0) < 0$ , we get

$$\begin{split} \int_0^T \Big[ \frac{Kt^{\alpha}}{\Gamma(\alpha+1)} + L + \frac{Mt^{\alpha-\beta}}{\Gamma(\alpha-\beta+1)} + N \int_0^t k_1(t,s) ds \\ &+ P \int_0^T h_1(t,s) ds \Big] dt > 1, \end{split}$$

which is contradiction.

## **2.4. Lemma.** If (2.3) holds. Then the linear problem

(2.4) 
$$\begin{cases} u'(t) = g(t) - KI^{\alpha}u(t) - Lu(t) - ML^{\alpha-\beta}u(t) - NT_1u(t) - PS_1u(t), \\ u(0) = x^*, g \in C(J, \mathbb{R}), \ 0 < \beta \le \alpha \le 1, \end{cases}$$

has a unique solution  $u^* \in C^1(J, \mathbb{R})$ .

*Proof.* We know that,  $u(t) \in C^1(J, \mathbb{R})$  is a solution of (2.4) if and only if  $u(t) \in C(J, \mathbb{R})$  is a solution of the following integral equation

$$u(t) = x^* e^{-\int_0^t L ds} + \int_0^t e^{-\int_s^t L d\tau} \Big(g(s) - K I^{\alpha} u(s) - M I^{\alpha - \beta} u(s) - N T_1 u(s) - P S_1 u(s) \Big) ds$$
  
=  $A u(t).$ 

1414

For any  $u, v \in C(J, \mathbb{R})$ , we show that A is a contraction operator.

$$\begin{split} |Au(t) - Av(t)| &= \left| \int_{0}^{t} e^{L(s-t)} \Big[ g(s) - KI^{\alpha} u(s) - MI^{\alpha-\beta} u(s) - NT_{1}u(s) - PS_{1}u(s) ds \right] \\ &- \int_{0}^{t} e^{L(s-t)} \Big[ g(s) - KI^{\alpha} v(s) - MI^{\alpha-\beta} v(s) - NT_{1}v(s) - PS_{1}v(s) \Big] ds \right| \\ &= \left| \int_{0}^{t} e^{L(s-t)} \Big[ K(I^{\alpha}(v-u)(s)) + M(I^{\alpha-\beta}(v-u)(s)) + N(T_{1}(v-u)(s)) + P(S_{1}(v-u)(s)) \Big] ds \right| \\ &\leq \int_{0}^{T} \left| K(I^{\alpha}(v-u)(s)) + M(I^{\alpha-\beta}(v-u)(s)) + N(T_{1}(v-u)(s)) + P(S_{1}(v-u)(s)) \right| ds \\ &\leq \int_{0}^{T} \Big[ \frac{Ks^{\alpha}}{\Gamma(\alpha+1)} + \frac{Ms^{\alpha-\beta}}{\Gamma(\alpha-\beta+1)} + N \int_{0}^{t} k_{1}(t,s) ds \\ &+ P \int_{0}^{T} h_{1}(t,s) ds \Big] ds ||u-v||. \end{split}$$

Therefore, by condition (2.3), it follows

$$||Au - Av|| < ||u - v||.$$

Thus, by Banach contraction principle A has a unique fixed point  $u^*$ , which is unique solution of (2.4).

#### 2.1. Theorem. Let the following assumptions hold:

• (H<sub>1</sub>) There exist  $u_0, v_0 \in C^1(J, \mathbb{R})$  satisfying  $u_0(t) \leq v_0(t), \ \forall t \in J$ ,

(2.5) 
$$\begin{cases} u'_0(t) \le f(t, I^{\alpha} u_0(t), u_0(t), I^{\alpha-\beta} u_0(t), T_1 u_0(t), S_1 u_0(t)), & t \in J, \\ u_0(0) \le x^*, & 0 < \beta \le \alpha \le 1, \end{cases}$$

and  $v_0$  satisfies inverse inequalities of (2.5).

•  $(H_2)$  There exist constants  $K, L, M, N, P \ge 0$  which satisfy condition (2.3) and

$$\begin{split} f(t,x,y,z,v,w) - f(t,\bar{x},\bar{y},\bar{z},\bar{v},\bar{w}) &\geq -K(x-\bar{x}) - L(y-\bar{y}) - M(z-\bar{z}) \\ &- N(u-\bar{u}) - P(w-\bar{w}). \end{split}$$

where  $I^{\alpha}u_{0}(t) \leq \bar{x} \leq x \leq I^{\alpha}v_{0}(t), \ u_{0}(t) \leq \bar{y} \leq y \leq v_{0}(t), \ I^{\alpha-\beta}u_{0}(t) \leq \bar{z} \leq z \leq I^{\alpha-\beta}v_{0}(t), \ T_{1}u_{0}(t) \leq \bar{v} \leq v \leq T_{1}v_{0}(t), \ S_{1}u_{0}(t) \leq \bar{w} \leq w \leq S_{1}v_{0}(t) \ \forall t \in J.$ 

Then there exist monotone iterative sequences  $\{u_n\}, \{v_n\} \subset [u_0, v_0]$  which converge uniformly to the extremal solutions  $u^*, v^*$  of (2.1), respectively, where  $\{u_n\}, \{v_n\}$  are defined by

$$u_{n}(t) = x^{*}e^{-\int_{0}^{t}Lds} + \int_{0}^{t}e^{-\int_{s}^{t}Ld\tau} \Big[f\Big(s, I^{\alpha}u_{n-1}(s), u_{n-1}(s), I^{\alpha-\beta}u_{n-1}(s)\Big)$$
$$-KI^{\alpha}(u_{n}-u_{n-1})(s) - L(u_{n}-u_{n-1})(s) - MI^{\alpha-\beta}(u_{n}-u_{n-1})(s)$$
$$-N(T_{1}(u_{n}-u_{n-1})(s)) - P(S_{1}(u_{n}-u_{n-1})(s))\Big]ds,$$

 $\operatorname{and}$ 

$$v_{n}(t) = x^{*}e^{-\int_{0}^{t}Lds} + \int_{0}^{t}e^{-\int_{s}^{t}Ld\tau} \Big[f\Big(s, I^{\alpha}v_{n-1}(s), v_{n-1}(s), I^{\alpha-\beta}v_{n-1}(s), T_{1}v_{n-1}(s), S_{1}v_{n-1}(s)\Big) - KI^{\alpha}(v_{n}-v_{n-1})(s) - L(v_{n}-v_{n-1})(s) - MI^{\alpha-\beta}(v_{n}-v_{n-1})(s) - N(T_{1}(v_{n}-v_{n-1})(s)) - P(S_{1}(v_{n}-v_{n-1})(s))\Big]ds.$$

Also,

$$u_0 \leq u_1 \leq \ldots \leq u_n \leq \ldots \leq u^* \leq v^* \leq \ldots \leq v_n \leq \ldots \leq v_1 \leq v_0$$

*Proof.* For  $\eta \in [u_0, v_0]$ , we consider

(2.6) 
$$\begin{cases} u'(t) = g_{\eta}(t) - KI^{\alpha}u(t) - Lu(t) - MI^{\alpha-\beta}u(t) \\ -N(T_{1}u(t)) - P(S_{1}u(t)) \\ u(0) = x^{*}, \ 0 < \beta \le \alpha \le 1, \end{cases}$$

where

$$g_{\eta}(t) = f\left(t, I^{\alpha}\eta(t), \eta(t), I^{\alpha-\beta}\eta(t), T_{1}\eta(t), S_{1}\eta(t)\right)$$
$$+ KI^{\alpha}\eta(t) + L\eta(t) + MI^{\alpha-\beta}\eta(t)$$
$$+ N(T_{1}\eta(t)) + P(S_{1}\eta(t)).$$

By Lemma (2.4), we know (2.6) has a unique solution  $u \in C^1(J, \mathbb{R})$ . Denote an operator  $A : [u_0, v_0] \to C(J, \mathbb{R})$  by  $u = A\eta$ , then

$$A\eta = x^* e^{-Lt} + \int_0^t e^{L(s-t)} \Big[ f\Big(s, I^{\alpha} \eta(s), \eta(s), I^{\alpha-\beta} \eta(s), T_1 \eta(s), S_1 \eta(s) \Big) \\ + K I^{\alpha} \eta(s) + L \eta(s) + M I^{\alpha-\beta} \eta(s) + N(T_1 \eta(s)) + P(S_1 \eta(s)) \\ - K I^{\alpha} u(s) - L u(s) - M I^{\alpha-\beta} u(s) - N(T_1 u(s)) - P(S_1 u(s)) \Big] ds.$$

Now, we show that  $u_0 \leq Au_0$ ,  $Av_0 \leq v_0$  and A is nondecreasing. For the first claim, let  $u_1 = Au_0$ ,  $p(t) = u_1(t) - u_0(t)$ . we show that  $p(t) \geq 0$ . By  $(H_1)$ , we get that

$$\begin{cases} p'(t) \ge -KI^{\alpha}p(t) - Lp(t) - MI^{\alpha-\beta}p(t) \\ -N(T_1p(t)) - P(S_1p(t)), \\ p(0) = u_1(0) - u_0(0) = Au_0(0) - u_0(0) \ge 0. \end{cases}$$

Hence, by Lemma (2.3)  $p(t) \ge 0$ . Similarly, we can show  $Av_0 \le v_0$ . Now, we show that A is nondecreasing. Let  $u_1 = Au_0$ ,  $v_1 = Av_0$  and  $p(t) = v_1(t) - u_1(t)$ .

1416

By  $(H_2)$ , we have

$$\begin{cases} p'(t) \ge -KI^{\alpha}p(t) - L(t) - MI^{\alpha-\beta}p(t) \\ -N(T_1p(t)) - P(S_1p(t)), \\ p(0) = v_1(0) - u_1(0) > 0. \end{cases}$$

So A is nondecreasing.

Next, let  $u_n = Au_{n-1}, v_n = Av_{n-1}, n = 1, 2, \dots$  By the properties of the operator A, we obtain that

$$u_0 \le u_1 \le \dots \le u_n \le \dots \le u^* \le v^* \le \dots \le v_n \le \dots \le v_1 \le v_0.$$

Clearly,  $u_n, v_n$  satisfy

$$\begin{cases} u'_{n}(t) = f(t, I^{\alpha}u_{n-1}, u_{n-1}, I^{\alpha-\beta}u_{n-1}, T_{1}u_{n-1}, S_{1}u_{n-1}) \\ -K(I^{\alpha}(u_{n} - u_{n-1})) - L(u_{n} - u_{n-1}) - M(I^{\alpha-\beta}(u_{n} - u_{n-1})) \\ -N(T_{1}(u_{n} - u_{n-1})) - P(S_{1}(u_{n} - u_{n-1})), \\ u_{n}(0) = x^{*}, \end{cases}$$
$$\begin{cases} v'_{n}(t) = f(t, I^{\alpha}v_{n-1}, v_{n-1}, I^{\alpha-\beta}v_{n-1}, T_{1}v_{n-1}, S_{1}v_{n-1}) \\ -K(I^{\alpha}(v_{n} - v_{n-1})) - L(v_{n} - v_{n-1}) - M(I^{\alpha-\beta}(v_{n} - v_{n-1})) \\ -N(T_{1}(v_{n} - v_{n-1})) - P(S_{1}(v_{n} - v_{n-1})), \\ v_{n}(0) = x^{*}. \end{cases}$$

The sequences  $u_n, v_n$  are uniformly bounded and equicontinuous, so by Arzela-Ascoli Theorem, we find that  $\lim_{n\to\infty} u_n(t) = u^*(t)$  and  $\lim_{n\to\infty} v_n(t) = v^*(t)$  uniformly on J, and  $u^*(t), v^*(t)$  are solutions of (2.1).

Finally, we prove that  $u^*, v^*$  are the extremal solutions of (2.1) in  $[u_0, v_0]$ . Let  $w \in [u_0, v_0]$ be any solution of (2.1), then Aw = w. By  $u_0 \le w \le v_0$  and the properties of A, we have

$$u_n \le w \le v_n, \quad n = 1, 2, \dots$$

Thus, taking limit as  $n \to \infty$ , we have  $u^* \le w \le v^*$ . That is,  $u^*, v^*$  are the extremal solutions of (2.1) in  $[u_0, v_0]$ . 

This completes the proof.

#### 3. Main result

In this section we prove the existence of extremal solutions of (1.1). Let  $C_{1-\alpha}(J,\mathbb{R}) = \{ u \in C(0,T]; t^{1-\alpha}u \in C(J,\mathbb{R}) \}$  and  $DC_{1-\alpha}(J,\mathbb{R}) = \{ u \in C_{1-\alpha}(J,\mathbb{R}); \ D^{\alpha}u \in C^{1}(J,\mathbb{R}) \}.$ 

#### **3.1. Theorem.** Assume that:

f(t, x, y, z,

 $(H'_1)$  There exist  $y_0, z_0 \in DC_{1-\alpha}(J, \mathbb{R})$  such that  $y_0(t) \leq z_0(t)$  and  $D^{\alpha}y_0(t) \leq D^{\alpha}z_0(t)$ , are lower and upper solution of (1.1),

(3.1) 
$$\begin{cases} (D^{\alpha}y_0(t))' \leq f(t, y_0(t), D^{\alpha}y_0(t), D^{\beta}y_0(t), Ty_0, Sy_0(t)) \\ D^{\alpha}y_0(0) \leq x^*, \quad t^{1-\alpha}y_0(t)|_{t=0} = 0. \end{cases}$$

and  $z_0$  satisfies inverse inequalities of (3.1).

 $(H'_2)$  There exist constants  $K, L, M, N, P \ge 0$  which satisfy condition (2.3) such that

$$u, w) - f(t, \bar{x}, \bar{y}, \bar{z}, \bar{u}, \bar{w}) \ge -K(x - \bar{x}) - L(y - \bar{y}) - M(z - \bar{z}) - N(u - \bar{u}) - P(w - \bar{w}),$$

where  $y_0(t) \leq \bar{x} \leq x \leq z_0(t), \ D^{\alpha}y_0(t) \leq \bar{y} \leq y \leq D^{\alpha}z_0(t), \ D^{\beta}z_0(t) \leq \bar{z} \leq z \leq z$  $D^{\beta}z_0(t), \ Ty_0(t) \le \bar{u} \le u \le Tz_0(t), \ Sy_0(t) \le \bar{w} \le w \le Sz_0(t).$ 

Then there exist iterative sequences  $\{y_n\}$ ,  $\{z_n\}$  which converge uniformly to the extremal solutions  $y^*, z^*$  of (1.1), respectively.

*Proof.* Let  $D^{\alpha}x(t) = u(t)$  in (1.1), then Equation (1.1) is transformed into first order integro-differential equation (2.1). Now, we prove that all the conditions of Theorem (2.1) hold. Let  $u_0(t) = D^{\alpha}y_0(t), v_0(t) = D^{\alpha}z_0(t)$ , we have  $u_0(t) \leq v_0(t)$ . Also  $y_0(t) = I^{\alpha}u_0(t), z_0(t) = I^{\alpha}v_0(t)$ , so by  $(H'_1) u_0, v_0$  satisfy  $(H_1)$ . By  $(H'_2)$ , it is easy to see that the condition  $(H_2)$  holds. Therefore, by Theorem (2.1), we obtain that (2.1) has extremal solutions  $u^*, v^* \in C^1(J, \mathbb{R})$  in  $[u_0, v_0]$ . Let  $y^* = I^{\alpha}u^*, z^* = I^{\alpha}v^*$  so it follows that

(3.2) 
$$\begin{cases} D^{\alpha}y^{*}(t) = u^{*}(t) \\ t^{1-\alpha}y^{*}(t)|_{t=0} = 0 \end{cases}$$

Since  $u^*$  satisfies (2.1) and  $y^*$  satisfies (3.2), then  $y^*$  is a solution of (1.1). Similarly, we can show that  $z^*$  is a solution of (1.1). It is easy to show that  $y^*, z^*$  are extremal solutions of (1.1). This completes the proof.

#### 4. Example

Consider the following problem:

(4.1) 
$$\begin{cases} (D^{\frac{1}{2}}x(t))' = \frac{-1}{10}x(t) - \frac{1+t}{15}D^{\frac{1}{2}}x(t) - \frac{1+t^2}{20}D^{\frac{1}{4}}x(t) \\ -\frac{1+t^3}{30}\int_0^t tsx(s)ds - \frac{1+t^4}{40}\int_0^1 sx(s)ds, \quad t \in [0,1], \\ D^{\frac{1}{2}}x(0) = 0, \quad t^{\frac{1}{2}}x(t)|_{t=0} = 0, \end{cases}$$

where  $\alpha = \frac{1}{2}, \beta = \frac{1}{4}, k(t,s) = ts, h(t,s) = s$ . Here,

$$f(t, x, y, z, u, w) = \frac{-1}{10}x - \frac{1+t}{15}y - \frac{1+t^2}{20}z - \frac{1+t^3}{30}u - \frac{1+t^4}{40}w.$$

By easy computation, we have  $K = \frac{1}{10}, \ L = \frac{2}{15}, \ M = \frac{1}{10}, \ N = \frac{1}{15}, \ P = \frac{1}{20}.$  Also,

$$\begin{split} \int_0^T \Big[ \frac{Kt^{\alpha}}{\Gamma(\alpha+1)} + L + \frac{Mt^{\alpha-\beta}}{\Gamma(\alpha-\beta+1)} + N \int_0^t k_1(t,s) ds \\ &+ P \int_0^T h_1(t,s) ds \Big] dt = 0.324 < 1. \end{split}$$

Now, take  $u_0(t) = 0$ ,  $v_0(t) = t^2$ . It is easy to see that  $u_0$ ,  $v_0$  are lower and upper solution of (4.1). So all the conditions of Theorem (3.1) hold.

Thus there exist iterative sequences  $\{u_n\}, \{v_n\}$  which converge uniformly to the extremal solutions  $u^*, v^*$  of (4.1), respectively.

**Acknowledgement** The authors would like to thank the referee for giving useful suggestions and comments for the improvement of this paper.

#### References

 ASME Journal of Computational and Nonlinear Dynamics, Special Issue "Discontinuous and Fractional Dynamical Systems", Guest Editors: J. A. Tenreiro Machado, Albert Luo, vol. 3, Issue 2, 125 pages, April 2008, ISSN: 1555-1415.

[2] Jankowski, T. Initial value for neutral fractional differential equations involving a Riemann-Liouville derivative, Appl. Math. Comput. **219** (2013) 7772-7776.

[3] Journal of Vibration and Control, Sage Pub, Special Issue "Mathematical Methods in Engineering", vol. 13, n. 9-10, pp. 1207-1516, Sept. 2007, ISSN: 1077-5463, Guest Editors: K. Tas, J. A. Tenreiro Machado, Dumitru Baleanu.

- [4] Kilbas, A.A., Srivastava, H. M. and Trujillo, J. J. Theory and applications of fractional differential equations, North-Holland Mathematical Studies, vol. 204, Elsevier Science B.V., Amsterdam, 2006.
- [5] Ladde, G.S., Lakshmikantham, V. and Vatsala, A. S. Monotone Iterative Techniques for Nonlinear Differential Equations, Pitman, Boston, 1985.
- [6] Liu,Z., Sun, J. and Szanto, I Monotone iterative technique for Riemann-Liouville fractional integro-differential equations with advanced arguments, Results. Math. 63 (2013), 1277-1287.
- [7] Miller, K. S., Ross, B. An Introduction to the Fractional Calculus and Differential Equations, Wiley, New York, 1993.
- [8] Monje, C. A., Chen, Y., Vinagre, B. M., Xue, D. and Feliu, V. Fractional-Order Systems and Controls: Fundamentals and Applications, Springer, New York, NY, USA, 2010.
- [9] Oustaloup, A., Sabatier, J., Lanusse, P., Malti, R., Melchior, P. and Moze, M., An overview of the CRONE approach in system analysis, modeling and identification, observation and control, in Proceedings of the 17thWorld Congress, International Federation of Automatic Control (IFAC '08), pp. 14254-14265, Soul, Korea, July 2008.
- [10] Petras, I. Fractional-Order Nonlinear Systems: Modelling, Analysis and Simulation, Springer, Dordrecht, The Netherlands, 2011.
- [11] Podlubny, I. Fractional Differential Equations, Academic Press, San Diego, CA, 1999.
- [12] McRae, F. A. Monotone iterative technique and existence results for fractional differential equations, Nonlinear Anal. **71** (2009) 6093-6096.
- [13] Ramirez, J. D., Vatsala, A. S. Monotone iterative technique for fractional differential equations with periodic boundary conditions, Opuscula Math. **29** (2009) 289-304.
- [14] Tarasov, V. E. Fractional Dynamics: Applications of Fractional Calculus to Dynamics of Particles, Fields and Media, Nonlinear Physical Science. Springer, Beijing, Heidelberg (2011).
- [15] Tenreiro Machado, J., Kiryakova, V. and Mainardi, F. A poster about the recent history of fractional calculus, Fract. Calc. Appl. Anal. 13, No 3 (2010), 329-334.
- [16] Tenreiro-Machado, J. A., Galhano, A. M. and Trujillo, J. J. Science Metrics on Fractional Calculus Development Since 1966, Fract. Calc. Appl. Anal., 16, No 2 (2013), pp. 479-500.
- [17] Uchaikin, V. V. Fractional Derivatives for Physicists and Engineers, Volume I Background and Theory; Volume II Applications, Series: Nonlinear Physical Science, Springer Jointly published with Higher Education Press, 2013.
- [18] Wang, G. Monotone iterative technique for boundary value problems of a nonlinear fractional differential equations with deviating arguments, J. Comput. Appl. Math. **236** (2012) 2425-2430.
- [19] Wang, G., Agarwal, R. P. and Cabada, A. Existence results and the monotone iterative technique for systems of nonlinear fractional differential equations, Appl. Math. Lett. 25 (2012) 1019-1024.
- [20] Wang, G., Baleanu, D. and Zhang, L. Monotone iterative method for a class of nonlinear fractional differential equations, Frac. Calc. Appl. Anal. **15** (2012) 244-252.
- [21] Wei, Z., Li, G. and Che, J. Initial value problems for fractional differential equations involving Riemann-Liouville sequential fractional derivative, J. Math. Anal. Appl. **367** (2010) 260-272.
- [22] Zhang, S. Monotone iterative method for initial value problem involving Riemann-Liouville fractional derivatives, Nonlinear Anal. **71** (2009) 2087-2093.