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Some Fixed Point Theorems IV

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Some Fixed Point Theorems IV

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ABSTRACT

Results on fixed points have been proved for single-valued and multi-valued mappings satisfying a rational inequality.

I. INTRODUCTION

The well-known Banach fixed point theorem states that a contraction mapping of a complete metric space into itself has a unique fixed point. In recent years, this celebrated theorem has been extended and generalized in various way by putting conditions either on the mapping or on the space. For a quite upto date information, books by Singh [16] and Smart [17] are worth-mentioning.

More recently, Khan [8] has extended contraction principle through a symmetric rational expression and obtained the following result.

Theorem A. Let (X,d) be a complete metric space and T a selfmapping on X for which

$$(*) \quad \ d(Tx,Ty) \ \leq \ K \ \left\{ \begin{array}{ccc} \frac{d(x,Tx) \ d(x,Ty) \ + \ d(y,Ty) \ d(y,Tx)}{d(x,Ty) \ + \ d(y,Tx)} \end{array} \right\}$$

holds for all x,y∈X, 0 < K < 1. Then T has a unique fixed point.

The mapping T satisfying (*) has been extensively studied by various authors e.g. Khan [8], [9], [10], [11], [12]. Fisher and Khan [4], Ray and Singh [15] and Fisher [3].

It was later shown by Fisher [3] that the Theorem A was incorrect as it stood and needed the extra condition, d(x,Ty) + d(y,Tx) = 0 implies that d(Tx,Ty) = 0, for the theorem to hold. Fisher [3] also gave an example to support his result.

The purpose of this paper is to unify the results of Khan [8] and Banach under the observation of Fisher [3].

II. RESULTS FOR SINGLE-VALUED MAPPINGS

We first prove a fixed point theorem for a bi-metric space (X,d,∂) where d and ∂ are two metrics on the set X.

Definition 2.1 (Ciric [1]). A mapping T of a metric space X into itself is said to be orbitally continuous if $\lim_{n\to\infty} T^{n_i} x = u$ implies that

$$\lim_{i\to\infty} T(T^{n_i} x) = Tu \text{ for each } x \in X.$$

It is well-known that every continuous mapping of X into itself is orbitally continuous, but the converse is not true (e.g. Ciric [1]). Definition 2.2 (Jaggi [7]). For $x_0 \in X$, let $O(x_0,T)$ denote the orbit of T at x_0 where T is a self-mapping of a metric space X. Then T is said to be x_0 -orbitally continuous if T: $O(x_0,T) \to X$, is continuous.

It is well-known that a mapping may be x_0 -orbitally continuous for some $x \in X$ without being orbitally continuous (e.g. Jaggi [7]).

Theorem 2.3. Let T be a self-mapping of a bi-metric space (X, d, ∂) such that following hold:

(i)
$$d(x,y) \le \partial(x,y)$$
, for all $x,y \in X$

(ii) there are non-negative numbers $\alpha{,}\beta$ with $\alpha{+}\beta{\,}<1$ and for which T satisfies

$$\partial(Tx,Ty) \; \leq \; \alpha \; \left\{ \; \frac{\partial(x,Tx) \;\; \partial(x,Ty) \;\; + \; \partial(y,Ty) \;\; \partial(y,Tx)}{\partial(x,Ty) \;\; + \; \partial(y,Tx)} \;\; \right\} \;\; + \; \beta \;\; \partial(x,y),$$

for all $x,y \in X$, when $\partial(x,Ty) + \partial(y,Tx) \neq 0$.

Further,
$$\partial(Tx,Ty) = 0$$
 if $\partial(x,Ty) + \partial(y,Tx) = 0$;

(iii) there exists some point $x_0 \in X$ such that the sequence $\{T^n | x_0\}$

of interates has a subsequence $\{T^{n_1} x_0\}$ converging to ξ with respect to d.

(iv) T is x₀-continuous with respect to d.

Then T has a unique fixed point.

Proof. Let $x_n = T^n x_0$, Then we have

$$\partial(x_n,x_{n+1}) \ = \ \partial(Tx_{n-1},\ Tx_n)$$

$$\leq \alpha \, \left\{ \, \frac{ \, \left(\partial(x_{n-1}, \; x_n) \partial(x_{n-1}, \; x_{n+1}) + \partial(x_n, x_{n+1}) \partial(x_n, x_n) \, \right. }{ \partial(x_{n-1}, \; x_{n+1}) + \partial(x_n, x_n)} \, \, \right\} + \beta \, \, \partial(x_{n-1}, \; x_n)$$

=
$$(\alpha+\beta)$$
 δ (x_{n-1},x_n) if $x_{n-1} \neq x_{n+1}$. However if

 $x_{n-1}=x_{n+1}$ then condition of theorem imply that $x_{n-1}=x_n=x_{n+1}$. Thus x_{n-1} would be a fixed point of T. Put $k=(\alpha+\beta)$. Then k<1 says that $\{T^n\ x_o\}$ is a Cauchy sequence with respect to ∂ .

So in view of (1) $\{T^n \ x_o\}$ is also a Cauchy sequence with respect to d. Due to (iv), it follows that $\{T^n \ x_o\}$ converges to ξ with respect to d. Now x_o -continuity of T with respect to d yields

$$T\xi = T(\lim_{n\to\infty} T^n | x_0) = \lim_{n\to\infty} T^{n+1} | x_0 = \xi.$$

Thus ξ is a fixed point of T. For unicity of ξ , consider $\eta \neq \xi$ such that $\eta = T\eta$. Then $\partial(\xi,\eta) > 0$. Also,

$$\partial(\eta,\xi) = \partial(T\eta,T\xi) \leq \alpha \left\{ \begin{array}{c} \frac{\partial(\eta,T\eta)\partial(\eta,T\xi) + \partial(\xi,T\xi)\partial(\xi,T\eta)}{\partial(\eta,T\xi) \ + \ \partial(\xi,T\eta)} \end{array} \right\} + \beta \ \partial(\eta,\xi),$$

$$\leq \beta \ \partial(\xi,\eta).$$

Thus

$$(1-\beta) \ \partial(\eta,\xi) \leq 0,$$

implying thereby $\partial(\xi,\eta) = 0$. So $\xi = \eta$.

Remarks. (1) For $\alpha = 0$, Theorem 2.3 reduces to that of Maia [13].

- (ii) When $\beta=0$ and $\partial=d$, Theorem 2.3 is the main theorem of Khan [8].
- (iii) If X is equipped with n metrics $d_1, d_2, \ldots, d_n, \partial$ such that $d(x,y) \leq d_1(x,y) \leq d_2(x,y) \leq \ldots \leq d_{n-2} \leq \partial(x,y)$ for every $x,y \in X$, then the conclusion of Theorem 2.3 still holds.

Theorem 2.4. Let $T: X \to X$ be an orbitally continuous mapping on a metric space X such that

$$\text{(i)} \ \ d(Tx,Ty) < \alpha \ \left\{ \begin{array}{c} \frac{d(x,Tx)d(x,Ty) + d(y,Ty)d(y,Tx)}{d(x,Ty) + d(y,Tx)} \end{array} \right\} + \beta d(x,y)$$

for all $x,y \in X$, $\alpha + \beta = 1$ (α,β non-negative reals) whenever $d(x,Ty) + d(y,Tx) \neq 0$, and d(Tx,Ty) = 0 when d(x,Ty) + d(y,Tx) = 0.

(ii) For some $x_0 \in X$ the sequence $\{T^n \ x_0\}$ has a cluster point $\xi \in X$. Then ξ is a unique fixed point of T.

Proof. If $T^{k-1} x_0 = T^k x_0$ for some $k \in \mathbb{N}$, then $T^n x_0 = T^k x_0 = \xi$ for all $n \ge k$, so the result follows.

Assume now that $T^{k-1} x_0 \neq T^k x_0$ for all $k \in \mathbb{N}$, and let $\lim_{i \to \infty} T^{ni} x_0 = \xi$. Then for $T^{n-1} x_0$ and $T^n x_0$ in X we get $d(T^n x_0, T^{n+1} x_0)$

$$\leq \alpha \left\{ \begin{array}{l} \frac{d(T^{n-1}x_0,T^nx_0)d(T^{n-1}x_0,T^{n+1}x_0)+d(T^nx_0,T^{n+1}x_0)d(T^nx_0,T^nx_0)}{d(T^{n-1}x_0,T^{n+1}x_0)+d(T^nx_0,T^nx_0)} \\ + \beta \ d(T^{n-1}x_0,T^nx_0). \end{array} \right.$$

$$\begin{split} &\text{If } d(T^{n-1}\ x_0, T^{n+1}x_0) + d(T^nx_0, T^nx_0) = 0, \text{ we find that} \\ &T(T^{n-1}x_0) \ = \ T(T^nx_0). \ \text{So } T^nx_0 \text{ is a fixed point of } T. \end{split}$$

Otherwise, above inequality reduces to

$$d(T^n x_0, T^{n+1} x_0) \le (\alpha + \beta) d(T^{n-1} x_0, T^n x_0).$$

Hence

$$d(T^n x_0, T^{n+1} x_0) < d(T^{n-1} x_0, T^n x_0).$$

Therefore, the sequence $\{d(T^n \ x_0, \ T^{n+1} \ x_0)\}$ is a decreasing and hence is convergent sequence of positive real numbers. Further,

$$\lim_{t\to\infty}\ d(T^{n_1}x_0,\,T^{n_1+1}x_0)=d(\xi,\,T\xi),$$

and

implies that

$$\lim_{n\to\infty} \ d(T^n \, x_o, \ T^{n+1} \, x_o) \, = \, d(\xi, \, T\xi).$$

Also, orbital continuity of T gives $\lim_{i \to \infty} T^{n_i+1} x_0 = T\xi$,

$$\lim_{i \, \to \, \infty} T^{n_i \, + 2} x_{_0}. \, = \, T^2 \xi \, \, \text{and} \, \{ d(T^{n_i \, + 1} \, \, x_{_0}, \, T^{n_i \, + 2} \, x_{_0}) \} \, \subseteq \, \{ d(T^n \, \, x_{_0}, \, T^{n+1} \, \, x_{_0}) \}.$$

Above relations show that

$$d(T\xi, T^2\xi) = d(\xi, T\xi).$$

If $d(\xi, T\xi) > 0$, then one gets

$$d(T\xi,T^2\xi)\ <\alpha\ \left\{ \begin{array}{c} \frac{d(\xi,T\xi)d(\xi,T^2\xi)+d(T\xi,T^2\xi)d(T\xi,T\xi)}{d(\xi,T^2\xi)+d(T\xi,T\xi)} \end{array} \right\} +\beta d(T\xi,T^2\xi).$$

Then we have

$$\mathrm{d}(\mathrm{T}\xi,\mathrm{T}^2\xi) \ < \left(rac{lpha}{1-eta}
ight)\mathrm{d}(\xi,\mathrm{T}\xi).$$

So

$$d(T\xi, T^2\xi) < d(\xi, T\xi),$$

which is a contradiction. Hence ξ is a fixed point of T which is clearly unique.

Remark. For $\alpha = 0$, our Theorem 2.4 extends a theorem of Edelstein [2].

Theorem 2.5. Let T be a continuous densifying mapping of a complete metric space X into itself such that for all x, $y \in X$ there are real constants α_i , (i = 1,2,3,4), α and β satisfying $\alpha_1 + \alpha_2 + \alpha_3 \ge \alpha + \beta$, for which the inequality

$$\alpha_1F(Tx,Ty) + \alpha_2F(x,Tx) + \alpha_3F(y,Ty) + \alpha_4 \min \{F(x,Ty),F(y,Tx)\}$$

$$<\alpha \left\{ \frac{F(x,Tx) F(x,Ty) + F(y,Ty) F(y,Tx)}{F(x,Ty) + F(y,Tx)} \right\} + \beta F(x,y).$$

holds for $x, y \in X$ whenever $F(x,Ty) + F(y,Tx) \neq 0$, and F(Tx,Ty) = 0,

otherwise, a lower semi-continuous function $F\colon X\times X\to [0,\infty)$ with the property F(x,y)=0 if and only if x=y. If for some $x_0\in X$, the sequence of iterates $\{T^n\ x_0\}$ is bounded, then T has a fixed point.

Proof. For y = Tx, we have

 $\alpha_{1}F(Tx,T^{2}|x) + \alpha_{2}F(x,Tx) + \alpha_{3}F(Tx,T^{2}|x) + \alpha_{2}\min\ \{F(x,T^{2}|x),F(Tx,Tx)\}$

$$<\alpha\left\{\frac{F(x,Tx)F(x,T^2x)+F(Tx,T^2x)F(Tx,Tx)}{F(x,T^2x)+F(Tx,Tx)}\right\}+\beta F(x,Tx).$$

If $F(x,T^2 x) = 0$ then one gets $F(Tx,T^2 x) = 0$ which gives

T(Tx) = Tx. So(Tx) is a fixed point of T.

If $F(x,T^2 x) \neq 0$, it is clear that $x \neq Tx$. So we get

$$F(Tx,T^2~x)~< \left(\begin{array}{c} \alpha+\beta-\alpha_2 \\ \hline \alpha_1+\alpha_3 \end{array} \right)~F(x,Tx).$$

Hence

$$F(Tx,T^2 x) < F(x,Tx), x \neq Tx.$$

Then from Theorem 5 of Iseki [6], we find that T has a fixed point. Remark. Our Theorem 2.5 generalizes a fixed point Theorem of Furi and Vignoli [5] as well as Theorem 3 of Khan [11].

Theorem 2.4. Let X be a complete metric space and $\{T_n\}$ a sequence of mappings of X into itself. Suppose there are non-negative reals α,β with $\alpha+\beta<1$ such that for all x, y $\in X$ the inequality

$$d(T^p{}_ix,T_j{}^qy) \leq \alpha \left\{ \begin{array}{c} \frac{d(x,T_1{}^px)d(x,T_j{}^qy) + d(y,T_j{}^qy)d(y,T_i{}^px)}{d(x,T_j{}^qy) + d(y,T_i{}^px)} \end{array} \right\} + \beta d(x,y)$$

holds whenever $d(x,T_i^qy)+d(y,T_i^px) \neq 0$, and further

 $d(T^p_i x, T_i^q y) = 0$ if $d(x, T_j^q y) + d(y, T_i^p x) = 0$, where p,q are some positive integers.

Then the sequence $\{T_n\}$ has a unique common fixed point. **Proof.** Let $x_0 \in X$ be arbitrary. Construct a sequence $\{x_n\}$ as follows: $x_1 = T_i^p x_0, \ x_2 = T_j^q x_1, \ x_3 = T_i^p x_2, \dots$

$$x_n = T_n^p (x_{n-1})$$
, when n is odd

and

$$x_n = T_n^q (x_{n-1})$$
, when n is even,

Then, by a routine calculation, it follows that $\{x_n\}$ is a Cauchy sequence which has a limit u, (say) in X.

It is not hard to see that u is a unique common fixed point of the sequence $\{T_n\}$. This completes the proof.

Definition 2.7. A self-mapping T on a metric space (X,d) is said to be non-expansive if

$$d(Tx,Ty) \le d(x,y)$$
, for all $x, y \in X$.

It is well-known (e.g., Smart [17] or Singh [16]) that a non-expansive mapping on a complete metric space need not fix any point of the space. For such mappings, however, we have the following common fixed point theorem.

Theorem 2.8. Let T, T_1,T_2 be three self-mappings of a complete metric space (X,d) where T is non-expansive. Also for all $x, y \in X$, and non-negative numbers α, β with $\alpha+\beta < 1$, we have

(i)
$$d(T_1^px,T_2^qy)$$

whenever $d(x,T_2^qy) + d(y,T_1^px) \neq 0$, and $d(T_1^px,T_2^qy) = 0$, whenever $d(x,T_2^qy) + d(y,T_1^px) = 0$, for some positive integers p,q;

(ii) T commutes with T₂q.

Then there is a unique common fixed point of T, T_1 and T_2 .

Proof. Follows from Theorem 2.6 once we use the non-expansiveness of T in (i). So T_1 and T_2 have a unique common fixed point say ξ . Then to show that ξ is also a fixed point of T, consider

$$\begin{split} d(\xi, &T\xi) = \ d(T_1{}^p\xi TT_2{}^q\xi) \\ &= \ d(T_1{}^p\xi, &T_2{}^q(T\xi)) \end{split}$$

$$\leq \alpha \left\{ \begin{array}{c} \frac{d(T\xi,TT_{1}^{p}\xi)\ d(T\xi,T_{2}^{q}(T^{2}\xi))\ +\ d(T^{2}\xi,T_{2}^{q}T^{2}\xi)\ d(T^{2}\xi,TT_{1}^{p}\xi)}{d(T\xi,T_{2}^{q}T^{2}\xi)\ +\ d(T^{2}\xi,TT_{1}^{p}\xi)} \end{array} \right. \\ \left. +\ \beta\ d(T\xi,T^{2}\xi)\ =\ \beta\ d(T\xi,T^{2}\xi). \end{array} \right.$$

Again using non-expansive property of T and the fact $\beta < 1$, we find that $T\xi = \xi$. Hence ξ is a unique common fixed point of T, T_1 and T_2 .

This complettes the proof.

Remarks. (i) If T is the identity map, Theorem 2.8 reduces to Theorem 2.6. This would mean that T may have more than one fixed point, but the common fixed point of T, T_1 and T_2 is unique.

- (ii) As remarked above, only non-expansiveness of T by itself would not ensure a fixed point for T.
- (iii) In Theorem 2.8 one can take a sequence of self-mappings $\{T_n\}$ of X so as to prove that T, T_1 , T_2 ... have a unique common fixed point.

III. RESULTS FOR MULTI-VALUED MAPPINGS

Lastly, we prove multi-valued version of several results obtained previously. Throughout this section, we follow the notations of Nadler [14]. For a metric space (X, d), $A \subseteq X$, $B \subseteq X$, and $\varepsilon > 0$, we write

- (i) $CB(X) = \{A: A \text{ is a non-empty closed and bounded subset of } X\};$
 - (ii) $N(A,\varepsilon) = \{x \in X : d(x, a) < \varepsilon \text{ for some } a \in A\};$
 - (iii) $D(A,B) = \inf \{d(a,b): a \in A, b \in B\};$
 - (iv) $H(A,B) = \inf \{ \epsilon > o \colon N(B,\epsilon) \subseteq A \text{ and } N(A,\epsilon) \supset B \}.$

The space CB(X) is a metric space with respect to the distance function H(A,B) called the Hausdorrf metric.

Theorem 3.1. Let X be a complete metric space and $F:X \to CB(X)$ a continuous multi-valued mapping. Suppose that F satisfies the inequality

$$H(Fx,Fy) \leq \alpha \left\{ \begin{array}{c} \frac{D(x,Fx) \ D(x,Fy) + D(y,Fy) \ D(y,Fx)}{D(x,Fy) + D(y,Fx)} \end{array} \right\} + \beta \ d(x,y)$$

for $x, y \in X$, $0 \le \alpha$, β with $\alpha + \beta < 1$, whenever $D(x,Fy) + D(y,Fx) \ne 0$, and H(Fx,Fy) = 0 when D(x,Fy) + D(y,Fx) = 0. Then F has a fixed point.

Proof. Let $x_0 \in X$ be arbitrary and $x_1 \in FX_0$. We may assume that $H(Fx_0, Fx_1) > 0$, since otherwise $x_1 \in Fx_1$, which implies that x_1 is a fixed point of F.

Let a be any real number with 0 < a < 1 and $K = \alpha + \beta$. Since $H(Fx_0, Fx_1) < K^{-a} H(Fx_0, Fx_1)$ and $x_1 \in Fx_0$, by the definition of H, there exists $x_2 \in Fx_1$ such that

$$d(\mathbf{x}_1,\mathbf{x}_2) \ \leq \ \mathbf{K}^{-a} \ \mathbf{H}(\mathbf{F}\mathbf{x}_0,\mathbf{F}\mathbf{x}_1).$$

Let $H(Fx_1,Fx_2) > 0$. Then $H(Fx_1,Fx_2) < K^{-a} H(Fx_1,Fx_2)$, which implies the existence of $x_3 \in Fx_0$ with the property

$$d(x_2,x_3) \leq K^{-a} H(Fx_1,Fx_2).$$

Continuing in this fashion, we produce a sequence $\{x_n\}$ of points of X such that

$$x_{n+1} \, \in \, Fx_n \ \, \text{and} \ \, d(x_n, \, \, x_{n+1}) \, \, \leq \, \, K^{-a} \ \, H(Fx_{n-1}, \, \, Fx_n).$$

Now we shall prove that $\{x_n\}$ is actually a Cauchy sequence in X. For this consider the inequality

$$d(x_n, x_{n+1}) \leq K^{-a} H(Fx_{n-1}, Fx_n)$$

$$\leq \! K^{-a} \left[\begin{array}{c} \alpha \left\{ \frac{D(x_{n-1},\!Fx_{n-1})D(x_{n-1},\!Fx_n) + D(x_n,\!Fx_n)D(x_n,\!Fx_{n-1})}{D(x_{n-1},\!Fx_n) + D(x_n,\!Fx_{n-1})} \right\} \\ + \beta \left(d(x_{n-1},\!x_n) \right. \right]$$

 $\leq K^{-a} \ (\alpha+\beta) \ d(x_{n-1}, \ x_n) \ \leq \ K^{1^{-a}} \ d(x_{n-1}, \ x_n), \ \text{when} \ D(x_{n-1}, \ Fx_n) \neq \ 0.$ Clearly, $x_n \in Fx_{n-1} = Fx_n$ when $D(x_{n-1}, \ Fx_n) = 0$, This implies therefore that x_n is a fixed point of F.

From $K^{1-a}<1$ and $d(x_n,\,x_{n+1})\leq K^{1-a}$ $d(x_{n-1},\,x_n)$, we observe that $\{x_n\}$ is a Cauchy sequence in X and has a limit $z,\,say,\,Now$

$$D(z,Fz) \leq d(z,x_{n+1}) + D(x_{n+1}, Fz)$$

$$\leq d(z, x_{n+1}) + H(Fx_n, Fz)$$

$$\leq \! d(z,\!x_{n+1}) + \alpha \! \left\{ \begin{array}{l} \frac{D(x_n,\!Fx_n) \; D(x_n,\!F_z) \, + \, D(z,\!Fz) \; D(z,\!Fx_n)}{D(x_n,\!Fz) \, + \, D(z,\!Fx_n)} \end{array} \right\} + \beta \; d(x_n,\!z).$$

$$\leq d(z,\!x_{n+1}) + \left.\alpha \left\{\frac{d(x_n,\!x_{n+1})\;D(x_n,\!Fz) + D(z,\!Fz)\;d(z,\!x_{n+1})}{D(x_n,\!Fz) + D(z,\!Fx_n)}\right\} + \beta d(x_n,\!z).$$

Letting n tending to infinity; we get D(z,Fz) = 0,

As Fz is a closed subset of X, it follows that $z \in Fz$. Thus z is a fixed point of F, and the proof is complete.

Remarks.

- (i) For $\alpha = 0$, Theorem 3.1 reduces to a result of Nadler [14].
- (ii) Where $\beta=0$, we get a multivalued version of the main theorem of Khan [8].
- (iii) We observe that the continuity requirement of the mapping F in Theorem 3.1 can be waived if $\alpha = 0$.

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